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A characterization of the weighted version of McEliece–Rodemich–Rumsey–Schrijver number based on convex quadratic programming

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For any graph G , Luz and Schrijver [A convex quadratic characterization of the Lovász theta number, *SIAM J. Discrete Math.* **19**(2) (2005) 382–387] introduced a characterization of the Lovász number $\vartheta(G)$ based on convex quadratic programming. A similar characterization is now established for the weighted version of the number $\vartheta'(G)$, independently introduced by McEliece, Rodemich, and Rumsey [The Lovász bound and some generalizations, *J. Combin. Inform. Syst. Sci.* **3** (1978) 134–152] and Schrijver [A Comparison of the Delsarte and Lovász bounds, *IEEE Trans. Inform. Theory* **25**(4) (1979) 425–429]. Also, a class of graphs for which the weighted version of $\vartheta'(G)$ coincides with the weighted stability number is characterized.

Keywords: Lovász number; McEliece–Rodemich–Rumsey–Schrijver number; maximum weight stable set; combinatorial optimization; graph theory; quadratic programming.

Mathematics Subject Classification: 05C50, 05C69, 90C27, 90C25

1. Introduction

Let $G = (V, E)$ be a simple undirected graph where $V = \{1, 2, \dots, n\}$ and E are respectively the vertex and edge sets. Throughout this paper it will be supposed that G has at least one edge (i.e., E is nonempty) and the notation $ij \in E$ will be used to denote the edge linking vertices i and j of V . The adjacency matrix of G is the symmetric matrix $A_G \in \mathbb{R}^{n \times n}$ whose entries (i, j) are equal to 1 if $ij \in E$ and 0 otherwise. By replacing some or all of the ones of A_G with any real numbers such that the resulting matrix remains nonnull and symmetric, we obtain a so-called *weighted adjacency matrix* of G . Furthermore, an *extended weighted adjacency matrix* of G can be obtained if some or all entries corresponding to edges $ij \notin E$ in a weighted adjacency matrix of G are replaced with negative real numbers such that the resulting matrix remains nonnull and symmetric.

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A graph $G = (V, E)$ is said to be a weighted graph if each vertex $i \in V$ has assigned a positive weight $w_i \in \mathbb{R}^+$. Denoting by $w = (w_1, \dots, w_n) \in \mathbb{R}^n$ the vector of vertex weights, the weighted graph will be represented by (G, w) . In the sequel there will be no distinction between the (extended or not) weighted adjacency matrices of G and (G, w) .

A stable set (or independent set) of $G = (V, E)$ is a subset of vertices of V whose elements are pairwise nonadjacent. The stability number (or independence number) of G is defined as the cardinality of a largest stable set and is usually denoted by $\alpha(G)$. A maximum stable set of G is a stable set with $\alpha(G)$ vertices. More generally, if (G, w) is a weighted graph, we can talk about a maximum weight stable set of G which is defined as a stable set for which the sum of vertex weights is maximum. This maximum sum is referred to as the weighted stability number of (G, w) and will be denoted by $\alpha(G, w)$.

The problem of finding $\alpha(G)$ is NP-hard and the same happens with $\alpha(G, w)$, since this number equals $\alpha(G)$ in the unweighted case, i.e., when all vertex weights are equal to one. However several ways of approaching those numbers have been proposed in the literature (see, for example, [1, 5, 8, 11, 17] and the surveys [2, 19]).

For any graph G with at least one edge, the upper bound $v(G)$ on $\alpha(G)$ defined as the optimal value of the following convex quadratic programming problem was introduced in [12]:

$$P(G) \quad v(G) = \max\{2e^T x - x^T(H + I)x : x \geq 0\},$$

where, hereinafter, e denote the $n \times 1$ all ones vector, T stands for the transposition operation, I is the identity matrix of order n , $x = (x_1, \dots, x_n)^T \in \mathbb{R}^n$, $x \geq 0$ means that all coordinates x_i of vector x are non-negative and $H = A_G / (-\lambda_{\min}(A_G))$. (In what follows, $\lambda_{\min}(M)$ and $\lambda_{\max}(M)$ will denote respectively the smallest and the largest eigenvalues of a matrix M ; also, all considered vectors are column vectors.)

Since G has at least one edge, A_G is indefinite as its trace is zero. Hence $\lambda_{\min}(H) = -1$ and this guarantees the convexity of $P(G)$ because $H + I$ is positive semidefinite. Consequently, $v(G)$ can be computed in polynomial time.

The graphs that satisfy $\alpha(G) = v(G)$ were introduced in [12] and subsequently studied in [3, 4, 13]. They are currently known as graphs with convex- QP stability number (or convex- QP graphs, where QP means quadratic programming).

The upper bound $v(G)$ was extended to the weighted case in [14]. The obtained extension, denoted here by $v(G, w)$, constitutes an upper bound on $\alpha(G, w)$ which, similarly to the unweighted case, can be computed by solving a quadratic programming problem:

$$\begin{aligned} \alpha(G, w) &\leq v(G, w) \\ &= \max \left\{ 2w^T x - x^T \left(\frac{A_G}{-\lambda_{\min}(W^{-1/2} A_G W^{-1/2})} + W \right) x : x \geq 0 \right\}, \end{aligned} \quad (1)$$

where W is the diagonal matrix whose main diagonal elements are the coordinates of w (i.e., $W = \text{diag}(w_1, \dots, w_n)$) and $W^{-1/2}$ denote the inverse matrix of $W^{1/2} =$

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$\text{diag}(\sqrt{w_1}, \dots, \sqrt{w_n})$. Note that the problem in (1) is equivalent to the following:

$$v(G, w) = \max \left\{ 2\sqrt{w}^T x - x^T \left(\frac{W^{-1/2} A_G W^{-1/2}}{-\lambda_{\min}(W^{-1/2} A_G W^{-1/2})} + I \right) x : x \geq 0 \right\}, \quad (2)$$

where $\sqrt{w} = (\sqrt{w_1}, \dots, \sqrt{w_n})^T$ is the vector whose coordinates are the square roots of vector w coordinates. In fact, substituting $y = W^{1/2}x$ for x in (1) we obtain the problem in (2) if after the substitution we continue using x instead of y for denoting the variables vector. Note also that $W^{-1/2} A_G W^{-1/2}$ is indefinite (since the same happens with A_G) and that $\frac{W^{-1/2} A_G W^{-1/2}}{-\lambda_{\min}(W^{-1/2} A_G W^{-1/2})} + I$ is positive semidefinite. Then the quadratic programming problem in (2) is convex and hence can be solved in polynomial time.

The Lovász number, usually denoted by $\vartheta(G)$, was introduced in [10] and is probably the most famous upper bound on $\alpha(G)$. It can be computed in polynomial time as proved by Grötschel, Lovász and Schrijver [6] and many characterizations of $\vartheta(G)$ are known, some of them are given in [10] (see [8, 9] for a detailed treatment of the subject).

Luz and Schrijver [15] introduced another characterization of $\vartheta(G)$ which is based on convex quadratic programming. As a matter of fact, with the aim of relating the upper bounds $v(G)$ and $\vartheta(G)$, they considered the family of convex quadratic problems,

$$P(G, C) \quad v(G, C) = \max \{ 2e^T x - x^T (H_C + I) x : x \geq 0 \},$$

where C is a weighted adjacency matrix of G and $H_C = C / -\lambda_{\min}(C)$. As the adjacency matrix A_G , matrix C is also indefinite and consequently, since $\lambda_{\min}(H_C) = -1$, all problems $P(G, C)$ are convex. Observe in addition that $v(G, A_G) = v(G)$ and hence $P(G)$ belongs to the family of $P(G, C)$ problems.

In consequence, the following characterization of $\vartheta(G)$ based on convex quadratic programming was given (see [15, Theorem 4.2]):

$$\vartheta(G) = \min_C v(G, C) = \min_C \max_{x \geq 0} \{ 2e^T x - x^T (H_C + I) x \}, \quad (3)$$

where C is a weighted adjacency matrix of G .

The number usually denoted by $\vartheta'(G)$ was independently introduced by McEliece, Rodemich, and Rumsey [16] and Schrijver [18]. It is also an upper bound on the stability number $\alpha(G)$ which is generally sharper than $\vartheta(G)$ since the following inequalities hold for each graph G (see [18]):

$$\alpha(G) \leq \vartheta'(G) \leq \vartheta(G). \quad (4)$$

Two characterizations of $\vartheta'(G)$ are presented below which can be also seen in [18]. The first one is:

$$\vartheta'(G) = \min_{M \in \mathcal{M}(G)} \lambda_{\max}(M), \quad (5)$$

where the minimum is taken over the set $\mathcal{M}(G)$ of all symmetric matrices $M = [m_{ij}] \in \mathbb{R}^{n \times n}$ such that $m_{ij} = 1$ if $i = j$ and $m_{ij} \geq 1$ if $ij \notin E$.

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The second characterization of $\vartheta'(G)$ is dual of the previous one:

$$\vartheta'(G) = \max_{B \in \mathcal{B}(G)} e^T B e, \quad (6)$$

where the maximum is taken over the set $\mathcal{B}(G)$ of all non-negative symmetric positive semidefinite matrices $B = [b_{ij}] \in \mathbb{R}^{n \times n}$ such that $b_{ij} = 0$ for $ij \in E$ and $\text{Tr}(B) = 1$. ($\text{Tr}(B)$ denotes the trace of B .)

In this paper the characterization (3) is extended to the weighted version of $\vartheta'(G)$, which, for any weighted graph (G, w) , will be denoted by $\vartheta'(G, w)$. We begin, in Sec. 2, with some $\vartheta'(G, w)$ definitions and then, in Sec. 3, the new characterization of $\vartheta'(G, w)$ based on convex quadratic programming is deduced. In Sec. 4, the class of weighted graphs (G, w) for which $\alpha(G, w) = \vartheta'(G, w)$ is characterized and an example of such a graph is presented.

2. Defining $\vartheta'(G, w)$

Recall the notations \sqrt{w} , W , $W^{1/2}$ and $W^{-1/2}$ set out in Sec. 1 for weighted graphs (G, w) . The weighted version of Lovász number, usually denoted by $\vartheta(G, w)$, was introduced by Grötschel, Lovász and Schrijver [6] and studied in detail in [7–9]. In a similar way, the weighted version of $\vartheta'(G)$, i.e., $\vartheta'(G, w)$, is defined here by extending the characterization (5) as follows:

$$\vartheta'(G, w) = \min_{M \in \mathcal{M}(G)} \lambda_{\max}(W^{1/2} M W^{1/2}), \quad (7)$$

where, as before, $\mathcal{M}(G)$ is the set of all symmetric matrices $M = [m_{ij}] \in \mathbb{R}^{n \times n}$ such that $m_{ij} = 1$ if $i = j$ and $m_{ij} \geq 1$ if $ij \notin E$.

Since we are assuming that G has at least one edge, we eliminate the matrix ee^T from $\mathcal{M}(G)$. In fact, if $\vartheta'(G, w) = \lambda_{\max}(W^{1/2} ee^T W^{1/2}) = \lambda_{\max}(\sqrt{w} \sqrt{w}^T) = e^T w$, we would obtain the largest possible value of $\vartheta'(G, w)$ which is only attained if (G, w) has no edge (because, as it will be seen below, $\vartheta'(G, w) \leq \vartheta(G, w)$ and the largest possible value of $\vartheta(G, w)$ is $e^T w$, see [9]).

Let M be one of the above symmetric matrices. As $M \neq ee^T$ we have that $Q = ee^T - M \neq 0$ is an extended weighted adjacency matrix of (G, w) . Consequently, setting $M = ee^T - Q$, the characterization (7) can be written in the form

$$\vartheta'(G, w) = \min_Q \lambda_{\max}(\sqrt{w} \sqrt{w}^T - W^{1/2} Q W^{1/2}), \quad (8)$$

where Q is an extended weighted adjacency matrix of (G, w) .

We can also have a characterization of $\vartheta'(G, w)$ which is dual of (8) and generalizes (6):

$$\vartheta'(G, w) = \max_{B \in \mathcal{B}(G)} \sqrt{w}^T B \sqrt{w}, \quad (9)$$

where, as before, $\mathcal{B}(G)$ is the set of all non-negative symmetric positive semidefinite matrices $B = [b_{ij}] \in \mathbb{R}^{n \times n}$ such that $b_{ij} = 0$ for $ij \in E$ and $\text{Tr}(B) = 1$.

Using (9), the inequalities (4) can be easily generalized for weighted graphs.

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Proposition 1. *Let (G, w) be a weighted graph. Then $\alpha(G, w) \leq \vartheta'(G, w) \leq \vartheta(G, w)$.*

Proof. Note first that if the nonnegativity of $\mathcal{B}(G)$ matrices is relaxed, the maximum in (9) becomes $\vartheta(G, w)$ (see for example [8]). Hence, $\vartheta'(G, w) \leq \vartheta(G, w)$. On the other hand, considering the matrix $B = \frac{1}{\alpha(G, w)}xx^T$, where x is defined by $x_i = \sqrt{w_i}$ if $i \in S$ and $x_i = 0$ otherwise with S being a maximum weighted stable set of (G, w) , $B \in \mathcal{B}(G)$ and $\sqrt{w}^T B \sqrt{w} = \alpha(G, w)$. Consequently, $\alpha(G, w) \leq \vartheta'(G, w)$. \square

3. The New Characterization of $\vartheta'(G, w)$

Our first aim is to relate $\vartheta'(G, w)$ to a family of quadratic upper bounds on $\alpha(G, w)$ which includes the upper bound $v(G, w)$ given in (2). Thus, associated to a weighted graph (G, w) , consider the matrices

$$H_{C, w} = \frac{W^{-1/2}CW^{-1/2}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})},$$

where $C = [c_{ij}] \in \mathbb{R}^{n \times n}$ is any extended weighted adjacency matrix of G , and the convex quadratic programming problems

$$P(G, w, C) \quad v(G, w, C) = \max\{2\sqrt{w}^T x - x^T(H_{C, w} + I)x : x \geq 0\}.$$

Note that $v(G, w, C)$ generalizes the upper bound $v(G, w)$ given in (2) since $v(G, w) = v(G, w, A_G)$.

We show first that $v(G, w, C)$ is an upper bound on the weighted stability number $\alpha(G, w)$.

Proposition 2. *Let (G, w) be a weighted graph with at least one edge. For any extended weighted adjacency matrix $C = [c_{ij}]$ of (G, w) , $v(G, w, C)$ is the optimal value of a convex quadratic programming problem and verifies $\alpha(G, w) \leq v(G, w, C)$, i.e., $v(G, w, C)$ is an upper bound on $\alpha(G, w)$.*

Proof. The matrix $H_{C, w}$ is indefinite since its trace is null and not all its entries are null. Thus $\lambda_{\min}(H_{C, w}) = -1$ and this guarantees the convexity of $P(G, w, C)$ because $H_{C, w} + I$ is positive semidefinite.

To see that $v(G, w, C)$ is an upper bound on $\alpha(G, w)$ for all extended weighted adjacency matrices C , let S be a maximum weight stable set of (G, w) and x be the vector defined by $x_i = \sqrt{w_i}$ if $i \in S$ and $x_i = 0$ otherwise. Since x is a feasible solution of $P(G, w, C)$, we have

$$\begin{aligned} v(G, w, C) &\geq 2\sqrt{w}^T x - x^T H_{C, w} x \\ &= 2\alpha(G, w) - \alpha(G, w) - \frac{1}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} \sum_{i,j} \frac{c_{ij}}{\sqrt{w_i w_j}} x_i x_j \end{aligned}$$

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$$= \alpha(G, w) - \frac{1}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} \\ \times \left(\sum_{i \in V} \frac{c_{ii}}{w_i} x_i^2 + 2 \sum_{ij \in E} \frac{c_{ij}}{\sqrt{w_i w_j}} x_i x_j + 2 \sum_{ij \notin E} \frac{c_{ij}}{\sqrt{w_i w_j}} x_i x_j \right).$$

As $\lambda_{\min}(W^{-1/2}CW^{-1/2}) < 0$, $c_{ii} = 0$ for all $i \in V$, $x_i x_j = 0$ if $ij \in E$ and $c_{ij} \leq 0$ if $ij \notin E$, the inequality $v(G, w, C) \geq \alpha(G, w)$ is true for all extended weighted adjacency matrices C of (G, w) . \square

We now relate $\vartheta'(G, w)$ with the convex quadratic upper bounds $v(G, w, C)$. First, it is proved that $\vartheta'(G, w)$ is not worse than any $v(G, w, C)$ bound.

Theorem 1. *Let (G, w) be a weighted graph with at least one edge. Then, for any extended weighted adjacency matrix C of (G, w) , we have $\vartheta'(G, w) \leq v(G, w, C)$.*

Proof. Let C be an extended weighted adjacency matrix of (G, w) and suppose that $P(G, w, C)$ is not unbounded otherwise the theorem is true.

Let x be an optimal solution of $P(G, w, C)$. The Karush–Kuhn–Tucker conditions applied to this problem guarantee that the following conditions are true:

$$x \geq 0, \quad (H_{C,w} + I)x \geq \sqrt{w}, \quad \text{and} \quad x^T (H_{C,w} + I)x = \sqrt{w}^T x = v(G, w, C). \quad (10)$$

As $H_{C,w} + I$ is positive semidefinite we can write $H_{C,w} + I = U^T U$. Denoting the columns of U by u_1, \dots, u_n , define a matrix $M = [m_{ij}] \in \mathbb{R}^{n \times n}$ such that

$$m_{ij} = 1 - \frac{u_i^T u_j}{(c^T u_i)(c^T u_j)} \quad \text{if } i \neq j, \\ m_{ii} = 1,$$

where $c = v_w^{-1/2} Ux$ (we use v_w to abbreviate $v(G, w, C)$). By (10), we have

$$U^T c = v_w^{-1/2} U^T Ux \geq v_w^{-1/2} \sqrt{w}; \quad (11)$$

hence $M \in \mathcal{M}(G)$ since it is symmetric, $m_{ii} = 1$ and $m_{ij} \geq 1$ if $ij \notin E$ (as $u_i^T u_j \leq 0$ if $ij \notin E$ and $c^T u_i > 0$ for all i by (11)).

On the other hand, (11) implies that $\frac{w_i}{(c^T u_i)^2} \leq v_w$, for all i , and from (10) we can conclude that $c^T c = v_w^{-1} x^T (H_{C,w} + I)x = 1$. Thus we can write

$$-\sqrt{w_i} m_{ij} \sqrt{w_j} = \sqrt{w_i} \left(c - \frac{u_i}{c^T u_i} \right)^T \left(c - \frac{u_j}{c^T u_j} \right) \sqrt{w_j}$$

and

$$v_w - \sqrt{w_i} m_{ii} \sqrt{w_i} = w_i \left(c - \frac{u_i}{c^T u_i} \right)^2 + v_w - \frac{w_i}{(c^T u_i)^2}.$$

These equations guarantee that matrix $v_w I - W^{1/2} M W^{1/2}$ is positive semidefinite and hence $\lambda_{\max}(W^{1/2} M W^{1/2}) \leq v_w$. Finally, by (7), we conclude $\vartheta'(G, w) \leq v(G, w, C)$ as desired. \square

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The next theorem establishes the characterization of $\vartheta'(G, w)$ based on convex quadratic programming. The proof given below generalizes proof of [15, Theorem 4.2]. Along it and in the rest of this paper, to simplify the notation, we will sometimes use ϑ'_w instead of $\vartheta'(G, w)$.

Theorem 2. *Let (G, w) be a weighted graph with at least one edge. If Q attains the optimum in (8) then $\vartheta'(G, w) = v(G, w, C)$, where $C = WQW$.*

Consequently, the following characterization of $\vartheta'(G, w)$ is valid:

$$\vartheta'(G, w) = \min_C v(G, w, C) = \min_C \max_{x \geq 0} \{2\sqrt{w}^T x - x^T (H_{C,w} + I)x\}, \quad (12)$$

where $C = WQW$ is an extended weighted adjacency matrix of (G, w) .

Proof. Let Q be an extended weighted adjacency matrix of (G, w) attaining the optimum in (8). As $\vartheta'(G, w) = \lambda_{\max}(\sqrt{w}\sqrt{w}^T - W^{1/2}QW^{1/2}) \geq -\lambda_{\min}(W^{1/2} \times QW^{1/2})$, we will divide into two cases the proof of the equality $\vartheta'(G, w) = v(G, w, C)$, where $C = WQW$.

Case 1: $\vartheta'(G, w) = -\lambda_{\min}(W^{1/2}QW^{1/2})$.

Let x attain the optimum in $P(G, w, C)$. Then, using the positive semidefiniteness of $I - (\vartheta'_w)^{-1}(\sqrt{w}\sqrt{w}^T - W^{1/2}QW^{1/2})$, we have

$$\begin{aligned} v(G, w, C) &= 2\sqrt{w}^T x - x^T (H_{C,w} + I)x = 2\sqrt{w}^T x - x^T \left(\frac{W^{1/2}QW^{1/2}}{-\lambda_{\min}(W^{1/2}QW^{1/2})} + I \right) x \\ &= 2\sqrt{w}^T x - x^T [I + (\vartheta'_w)^{-1}W^{1/2}QW^{1/2} - (\vartheta'_w)^{-1}\sqrt{w}\sqrt{w}^T]x - (\vartheta'_w)^{-1}(\sqrt{w}^T x)^2 \\ &= 2\sqrt{w}^T x - x^T [I - (\vartheta'_w)^{-1}(\sqrt{w}\sqrt{w}^T - W^{1/2}QW^{1/2})]x - (\vartheta'_w)^{-1}(\sqrt{w}^T x)^2 \\ &\leq 2\sqrt{w}^T x - (\vartheta'_w)^{-1}(\sqrt{w}^T x)^2 \leq \vartheta'_w, \end{aligned}$$

since $[(\vartheta'_w)^{1/2} - (\vartheta'_w)^{-1/2}\sqrt{w}^T x]^2 \geq 0$. So, by Theorem 1, we have $\vartheta'(G, w) = v(G, w, C)$ for this case.

Case 2: $\vartheta'(G, w) > -\lambda_{\min}(W^{1/2}QW^{1/2})$.

Let B attain the optimum in (9). Since $\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}$ is positive semidefinite we have, by the Fejer's trace theorem,

$$\text{Tr}[B(\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2})] \geq 0.$$

On the other hand,

$$\begin{aligned} &\text{Tr}[B(\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2})] \\ &= \vartheta'_w \text{Tr}(B) - \text{Tr}(B\sqrt{w}\sqrt{w}^T) + \text{Tr}[B(W^{1/2}QW^{1/2})] \\ &= \vartheta'_w - \vartheta'_w + \text{Tr}[B(W^{1/2}QW^{1/2})] \\ &= \text{Tr}[B(W^{1/2}QW^{1/2})] \leq 0, \end{aligned}$$

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as B is non-negative and Q is an extended weighted adjacency matrix of (G, w) . Thus

$$\text{Tr}[B(\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2})] = 0$$

and, using the positive semidefiniteness of $\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}$ and B , we have $B(\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}) = O$, where O denotes the null matrix. Thus, the column space of B is orthogonal to the column space of $\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}$.

The inequality $\vartheta'_w(G) > -\lambda_{\min}(W^{1/2}QW^{1/2})$ implies that $\lambda_{\min}(\vartheta'_w I + W^{1/2}QW^{1/2}) > 0$ and hence $\text{rank}(\vartheta'_w I + W^{1/2}QW^{1/2}) = n$. Then $\text{rank}(\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}) \geq n-1$ and by the column spaces orthogonality, $\text{rank}(B) \leq 1$. As $\text{Tr}(B) = 1$, $\text{rank}(B) = 1$ and then $B = (\vartheta'_w)^{-1}xx^T$ for some vector x whose support is a stable set S . Since $\sqrt{w}^T B \sqrt{w} = \vartheta'_w$ and $\text{Tr}(B) = 1$, we can choose $x \geq 0$ and thus we have $\sqrt{w}^T x = x^T x = \vartheta'_w$. In addition, x is given by

$$x_i = \begin{cases} \sqrt{w_i} & \text{if } i \in S, \\ 0 & \text{if } i \notin S, \end{cases} \quad (13)$$

i.e., $x = W^{1/2}y$, where y is a characteristic vector of S . (To see this, let $z = (z_i)_{i=1, \dots, n}$ be a vector such that $z_i = \sqrt{w_i}$ if $i \in S$ and $z_i = 0$ if $i \notin S$. Then, $z^T x = \sqrt{w}^T x = \vartheta'_w$ and, using the Cauchy–Schwarz inequality, $(z^T x)^2 \leq (x^T x)(z^T z)$. So $\vartheta'_w \leq z^T z = \sum_{i \in S} w_i$, and by the maximality of ϑ'_w we have $z^T z = \vartheta'_w$. Hence, the Cauchy–Schwarz inequality is satisfied with equality and this implies $x = z$.)

Using once more the orthogonality of the column spaces of B and $\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}$, we conclude that $(\sqrt{w}\sqrt{w}^T - W^{1/2}QW^{1/2})x = \vartheta'_w x$, and hence $W^{1/2}QW^{1/2}x = \vartheta'_w(\sqrt{w} - x)$. Then x satisfies the Karush–Kuhn–Tucker conditions associated with $P(G, w, C)$ (recall (10)) as:

- $x \geq 0$;
- $(H_{C,w} + I)x = \left(\frac{W^{1/2}QW^{1/2}}{-\lambda_{\min}(W^{1/2}QW^{1/2})} + I \right)x = \frac{W^{1/2}QW^{1/2}x}{-\lambda_{\min}(W^{1/2}QW^{1/2})} + x = \frac{\vartheta'_w}{-\lambda_{\min}(W^{1/2}QW^{1/2})}(\sqrt{w} - x) + x \geq \sqrt{w}$, since $\vartheta'_w \geq -\lambda_{\min}(W^{1/2}QW^{1/2})$; and
- $x^T(H_{C,w} + I)x = \frac{\vartheta'_w}{-\lambda_{\min}(W^{1/2}QW^{1/2})}x^T(\sqrt{w} - x) + x^T x = \vartheta'_w$, since $x^T(\sqrt{w} - x) = 0$.

Consequently, by the positive semidefiniteness of $H_{C,w} + I$, the equality $\vartheta'(G, w) = v(G, w, C)$ is also true for Case 2.

Finally, the proved equality, the definition of Q and Theorem 1 imply the characterization (12). \square

4. A Class of Graphs for Which $\alpha(G, w) = \vartheta'(G, w)$

As a consequence of Theorem 2, a necessary and sufficient condition that characterizes the weighted graphs (G, w) for which $\alpha(G, w) = \vartheta'(G, w)$ is given.

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Theorem 3. *Let (G, w) be a weighted graph with at least one edge and Q an extended weighted adjacency matrix such that $C = WQW$ attains the optimum in (12). Then $\alpha(G, w) = \vartheta'(G, w)$ if and only if there is a maximum weight stable set S of (G, w) for which the following conditions hold:*

$$\sum_{j \in S} c_{ij} = 0, \quad \forall i \in S \quad (14)$$

and

$$-\lambda_{\min}(W^{1/2}QW^{1/2}) \leq \frac{1}{w_i} \sum_{j \in S} c_{ij}, \quad \forall i \notin S, \quad (15)$$

where c_{ij} denotes the entry (i, j) of matrix C .

Proof. Theorem 2 allows to conclude that $\alpha(G, w) = \vartheta'(G, w)$ if and only if $\alpha(G, w) = v(G, w, C)$, where $C = WQW$. We will prove that $\alpha(G, w) = v(G, w, C)$ holds if and only if conditions (14) and (15) are satisfied.

To begin with, suppose that these conditions hold for a maximum weight stable set S of (G, w) . If $x = W^{1/2}y$, where y is the characteristic vector of S , we have

$$\begin{aligned} & 2 \left(\frac{W^{-1/2}CW^{-1/2}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} + I \right) x \\ &= 2 \frac{W^{-1/2}Cy}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} + 2W^{1/2}y \\ &= \begin{cases} 2 \frac{1}{\sqrt{w_i}} \frac{\sum_{j \in S} c_{ij}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} + 2\sqrt{w_i} & \text{if } i \in S, \\ 2 \frac{1}{\sqrt{w_i}} \frac{\sum_{j \in S} c_{ij}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} & \text{if } i \notin S. \end{cases} \end{aligned}$$

Taking into account condition (14), we can write

$$2 \left(\frac{W^{-1/2}CW^{-1/2}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} + I \right) x = \begin{cases} 2\sqrt{w_i} & \text{if } i \in S, \\ 2 \frac{1}{\sqrt{w_i}} \frac{\sum_{j \in S} c_{ij}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} & \text{if } i \notin S. \end{cases} \quad (16)$$

On the other hand, let $s = (s_1, \dots, s_n)$ be given by

$$s_i = \begin{cases} 0 & \text{if } i \in S, \\ 2 \frac{1}{\sqrt{w_i}} \frac{\sum_{j \in S} c_{ij}}{-\lambda_{\min}(W^{-1/2}CW^{-1/2})} - 2\sqrt{w_i} & \text{if } i \notin S. \end{cases}$$

Note that $s \geq 0$ since $-\lambda_{\min}(W^{-1/2}CW^{-1/2}) = -\lambda_{\min}(W^{1/2}QW^{1/2})$ and we are assuming the truthfulness of condition (15). Then, from the definitions of x and s

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and taking into account equality (16), we can deduce the following conditions

$$x, s \geq 0, \quad x^T s = 0 \quad \text{and} \\ 2 \left(\frac{W^{-1/2} C W^{-1/2}}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} + I \right) x = 2\sqrt{w} + s,$$

which are the Karush–Kuhn–Tucker conditions for the problem $P(G, w, C)$. Consequently,

$$\begin{aligned} v(G, w, C) &= 2\sqrt{w}^T x - x^T \left(\frac{W^{-1/2} C W^{-1/2}}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} + I \right) x \\ &= 2\sqrt{w}^T x - x^T x - \frac{y^T C y}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} \\ &= 2\alpha(G, w) - \alpha(G, w) - \frac{\sum_{i \in S} (\sum_{j \in S} c_{ij})}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} \\ &= \alpha(G, w) - 0 = \alpha(G, w). \end{aligned}$$

Conversely, suppose that $\alpha(G, w) = v(G, w, C)$. We first prove that condition (14) is satisfied and that $x = W^{1/2}y$, where y is a characteristic vector of any maximum weight stable set S of (G, w) , is an optimal solution of problem $P(G, w, C)$. In fact, computing the objective function value of problem $P(G, w, C)$ for $x = W^{1/2}y$, we obtain

$$\begin{aligned} &2\sqrt{w}^T x - x^T \left(\frac{W^{-1/2} C W^{-1/2}}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} + I \right) x \\ &= 2\sqrt{w}^T x - x^T x - \frac{x^T W^{-1/2} C W^{-1/2} x}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} \\ &= \alpha(G, w) - \frac{\sum_{i \in S} (\sum_{j \in S} c_{ij})}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} \leq v(G, w, C) = \alpha(G, w). \end{aligned}$$

Therefore, $\sum_{i \in S} (\sum_{j \in S} c_{ij}) \geq 0$ as $-\lambda_{\min}(W^{-1/2} C W^{-1/2}) > 0$ and hence $\sum_{j \in S} c_{ij} = 0$ for all $i \in S$ since $c_{ii} = 0$ and $c_{ij} \leq 0$ for $ij \notin E$. Thus, condition (14) is verified and x yields an optimal solution of problem $P(G, w, C)$.

In addition, as $x = W^{1/2}y$ solves problem $P(G, w, C)$, the Karush–Kuhn–Tucker conditions imply that

$$2 \left(\frac{W^{-1/2} C W^{-1/2}}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} + I \right) x = 2\sqrt{w} + s,$$

with $s \geq 0$. It follows that, for each $i \notin S$, the corresponding line of the last equality is written as

$$2 \frac{1}{\sqrt{w_i}} \frac{\sum_{j \in S} c_{ij}}{-\lambda_{\min}(W^{-1/2} C W^{-1/2})} = 2\sqrt{w_i} + s_i,$$

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from which we conclude

$$-\lambda_{\min}(W^{-1/2}CW^{-1/2}) \leq \frac{1}{w_i} \sum_{j \in S} c_{ij},$$

taking into account that $s_i \geq 0$. As, once more, $-\lambda_{\min}(W^{-1/2}CW^{-1/2}) = -\lambda_{\min}(W^{1/2}QW^{1/2})$, condition (15) is valid and the theorem follows. \square

Also, as a consequence of Theorem 2, the next result states another sufficient condition for having $\alpha(G, w) = \vartheta'(G, w)$. Although the verification of this sufficient condition needs the computation of $\vartheta(G, w)$, in case it is satisfied the optimal solution of any element of a set of strictly convex quadratic programming problems is shown to yield a maximum weight stable set.

Theorem 4. *Let (G, w) be a weighted graph with at least one edge and Q be an extended weighted adjacency matrix of (G, w) attaining the optimum in (8). If $\vartheta'(G, w) > -\lambda_{\min}(W^{1/2}QW^{1/2})$ then $\alpha(G, w) = \vartheta'(G, w)$ and a maximum weight stable set of (G, w) can be obtained by solving, for any $\tau \in]-\lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w]$, the following convex quadratic programming problem:*

$$P(G, w, C, \tau) \quad v(G, w, C, \tau) = \max \left\{ 2\sqrt{w}^T x - x^T \left(\frac{W^{-1/2}CW^{-1/2}}{\tau} + I \right) x : x \geq 0 \right\},$$

where $C = WQW$.

Proof. From Case 2 of proof of Theorem 2, we know that if $\vartheta'_w > -\lambda_{\min}(W^{1/2}QW^{1/2})$ the vector $x = W^{1/2}y$ given in (13), with y being the characteristic vector of stable set that supports x , verifies $\sqrt{w}^T x = x^T x = \vartheta'_w$. Hence $\alpha(G, w) \geq w^T y = \sqrt{w}^T W^{1/2}y = \sqrt{w}^T x = \vartheta'_w$, i.e., $\alpha(G, w) = \vartheta'(G, w)$ as required in the theorem's first part.

To see the remaining part, recall that, as it is also stated in Case 2 of proof of Theorem 2, from the orthogonality of columns spaces of $B = (\vartheta'_w)^{-1}xx^T$ and $\vartheta'_w I - \sqrt{w}\sqrt{w}^T + W^{1/2}QW^{1/2}$, it can be concluded that $W^{1/2}QW^{1/2}x = \vartheta'_w(\sqrt{w} - x)$, where x is given in (13). Therefore, if $i \in S$, $x_i = \sqrt{w_i}$ and then

$$\sum_{j \in V} \sqrt{w_i w_j} q_{ij} x_j = 0 \Rightarrow \sum_{j \in V} \frac{\sqrt{w_i w_j} q_{ij}}{\tau} x_j = 0, \quad \forall \tau \in]-\lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w],$$

where q_{ij} is the (i, j) entry of matrix Q . Thus, for $i \in S$, the equalities

$$\sum_{j \in V} \frac{\sqrt{w_i w_j} q_{ij}}{\tau} x_j + x_i = \sqrt{w_i} + s_i, \tag{17}$$

where $s_i = 0$, are true for all $\tau \in]-\lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w]$.

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On the other hand, if $i \notin S$, $x_i = 0$ and then $W^{1/2}QW^{1/2}x = \vartheta'_w(\sqrt{w} - x)$ implies that

$$\sum_{j \in V} \sqrt{w_i w_j} q_{ij} x_j = \vartheta'_w \sqrt{w_i} \geq \tau \sqrt{w_i}, \quad \forall \tau \in] - \lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w].$$

Hence, for $i \notin S$ there exists $s_i \geq 0$ such that

$$\sum_{j \in V} \frac{\sqrt{w_i w_j} q_{ij}}{\tau} x_j = \sqrt{w_i} + s_i, \quad \forall \tau \in] - \lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w]. \quad (18)$$

From the equalities (17) and (18) we conclude that, for all $\tau \in] - \lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w]$, there exists a vector $s \geq 0$ such that x and s satisfy $x^T s = 0$ as well as the equality

$$\left(\frac{W^{1/2}QW^{1/2}}{\tau} + I \right) x = \sqrt{w} + s.$$

Consequently, for all $\tau \in] - \lambda_{\min}(W^{1/2}QW^{1/2}), \vartheta'_w]$, x satisfies the Karush–Kuhn–Tucker conditions associated with problem $P(G, w, WQW, \tau)$, hence it is an optimal solution of this problem. Since, for those values of τ , $P(G, w, WQW, \tau)$ is a strictly convex quadratic programming problem, solving it allows to obtain its unique solution. This is precisely the vector x given in (13) whose support is a maximum weight stable set of (G, w) . \square

The following property of weighted graphs verifying the sufficient condition of this last theorem can be asserted.

Corollary 4.1. *Let (G, w) be a weighted graph verifying the conditions of Theorem 4. If S is a maximum weight stable set of (G, w) then, for all $i \notin S$,*

$$\frac{1}{w_i} \sum_{j \in S} c_{ij} = \vartheta'(G, w), \quad \forall i \notin S, \quad (19)$$

where c_{ij} denotes the entry (i, j) of $C = WQW$. Consequently, the right-hand side of (15) equals $\vartheta'(G, w)$.

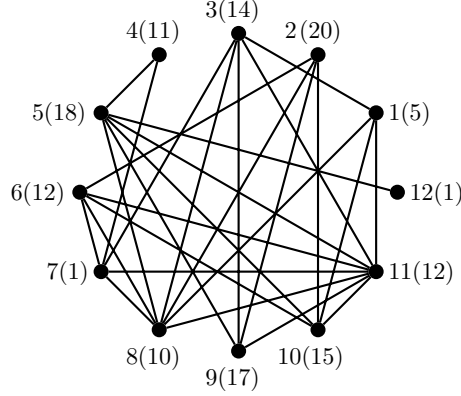
Proof. Consider once more the equality $W^{1/2}QW^{1/2}x = \vartheta'_w(\sqrt{w} - x)$ deduced in proof of Theorem 2, where $x = W^{1/2}y$ is given in (13), with y being the characteristic vector of stable set S that supports x . Hence $(W^{1/2}QW^{1/2} + \vartheta'_w I)W^{1/2}y = \vartheta'_w \sqrt{w}$ and, multiplying this equality on the left by $W^{1/2}$, we obtain $(C + \vartheta'_w W)y = \vartheta'_w w$. So, for $i \notin S$, row i of this system can be written as

$$\sum_{j \in S} c_{ij} = \vartheta'_w w_i,$$

since row i of Wy is null. Consequently, the corollary follows. \square

The above corollary allows to conclude that the weighted graphs verifying the sufficient condition of Theorem 4 also satisfy (15). This is mandatory since these

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Fig. 1. A weighted graph (G, w) (the weights in brackets) for which $\alpha(G, w) = \vartheta'(G, w)$.

graphs satisfy $\alpha(G, w) = \vartheta'(G, w)$. As an example, consider the weighted graph (G, w) depicted in Fig. 1 where $w = (5, 20, 14, 11, 18, 12, 1, 10, 17, 15, 12, 1)^T$. We have $\vartheta'(G, w) = 54 > 53.80 = -\lambda_{\min}(W^{1/2}QW^{1/2})$, with Q being an extended weighted adjacency matrix of G such that $\vartheta'(G, w) = \lambda_{\max}(\sqrt{w}\sqrt{w}^T - W^{1/2}QW^{1/2})$. Consequently, by Theorem 4, $\alpha(G, w) = \vartheta'(G, w)$, the vector

$$x = (0, 0, 0, 3.32, 0, 0, 0, 3.16, 4.12, 3.87, 0, 1)^T$$

solves problem $P(G, w, C)$ (where $C = WQW$), verifies $\sqrt{w}^T x = 54 = \vartheta'(G, w)$ and its support $S = \{4, 8, 9, 10, 12\}$ is a maximum weight stable set S of (G, w) .

On the other hand, by Corollary 4.1, we have that $\frac{1}{w_i} \sum_{j \in S} c_{ij} = \vartheta'(G, w) = 54$, for all $i \notin S$. Therefore, (15) holds since $-\lambda_{\min}(W^{1/2}QW^{1/2}) = 53.80$. As the equalities $\sum_{j \in S} c_{ij} = 0$, for all $i \in S$, are satisfied for this example, Theorem 3 also implies that $\alpha(G, w) = \vartheta'(G, w)$.

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